



Using vessel monitoring systems data to characterize movement patterns of the Pacific Salmon ocean troll fishery in response to variable oceanographic conditions

- Catherine Courtier (University of California, Davis)

Overview

Methods

- Transfer ecological methods to human systems to describe changes in:
 - Fishing locations of salmon fisheries
 - Associated behavioral states (e.g., fishing, searching)

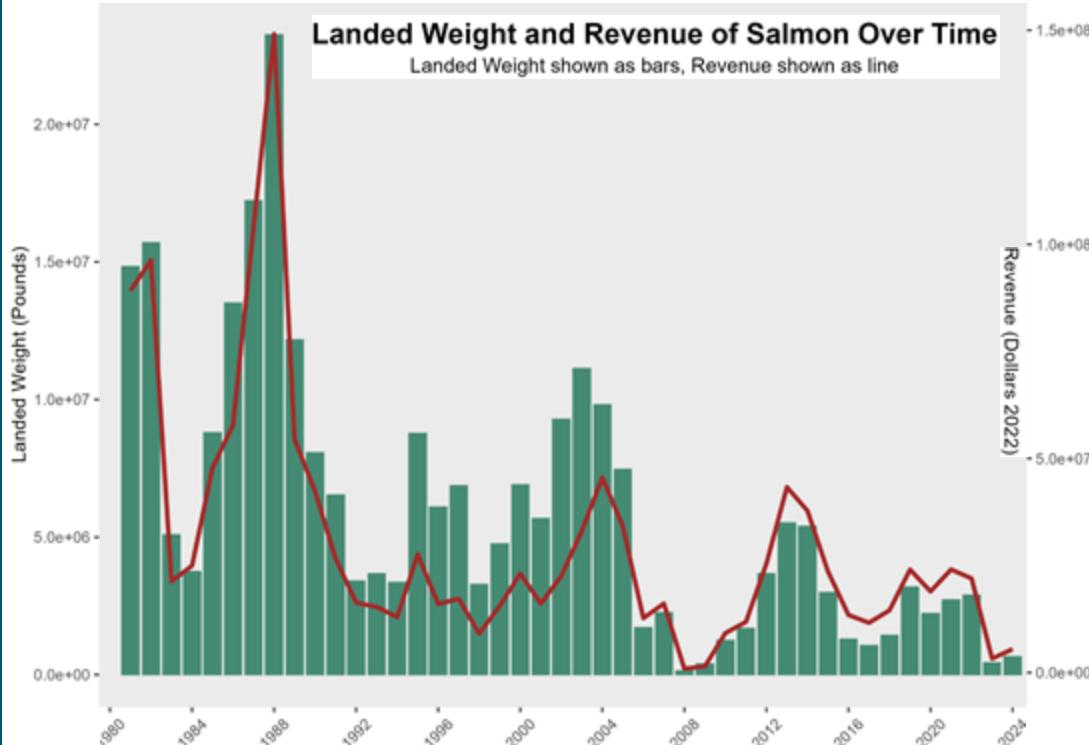
Preliminary Results:

- Methods were successfully validated by one independent data source
- Post marine heatwave (the "blob"), fishers spent more time searching for fish and less time fishing

Importance:

- Understanding this is useful for:
 - Conservation of threatened salmon stocks
 - Understanding how fishing costs change over time
 - Better estimates of CPUE
 - Minimizing bycatch

Rationale



- Location of fishing activity can reveal areas of:
 - High fishing intensity
 - Potential space-use conflict
- Changes in these locations can reveal:
 - How fishers respond to environmental change
 - Adaptive capacity of a fleet
- Climate change is projected to cause declines in landings revenue
 - Not felt evenly among geographic areas

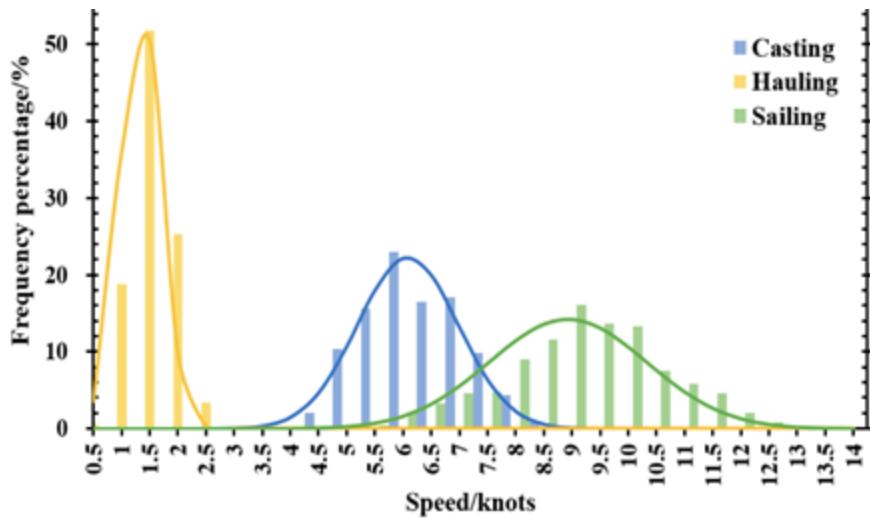
Data



- Pacific Salmon Ocean Troll Fishery (Chinook and coho)
 - Fishers who also fish for groundfish → ~20%
- Washington, Oregon, and California
- 2007 - 2023
- **Pacific Fisheries Information Network (PacFIN):**
 - Landings receipts data
 - Vessel monitoring systems (VMS) data
 - → New VMS-salmon landings “trip” data
- **Previous studies have used VMS data to assess:**
 - Spatial fishing behavior (Janette et al., 2010; O’Farrell et al., 2019; Li et al., 2022)
 - Fishing effort (Thoya et al., 2021; Zhao et al., 2021)
 - Fishing uncertainty (Ducharme-Barth & Ahrens 2017)

Characterizing Fisher Movement

- Can we assess how fisher movement behavior has changed in response to variable oceanographic conditions?
 - E.g., has time spent “searching” for fish increased over time as salmon shift their range into more suitable habitats and fishers adjust their behavior to find them?



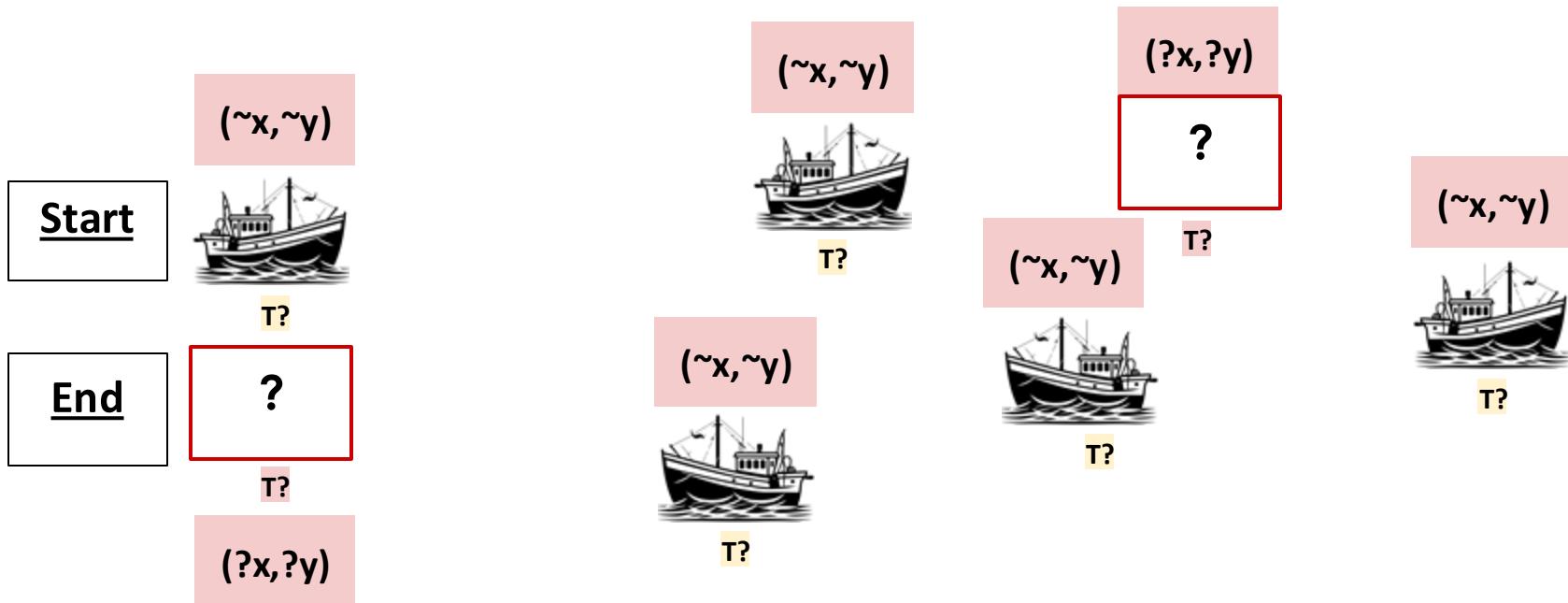
Source: Li et al. (2022) - Yellow Sea prawn fishery

Characterizing Fisher Movement

- **1) Methods from fisheries economics:**
 - Artificial neural networks; random forest models
 - Shrimp, Yellow Sea (Li et al., 2022); Reef fish, Gulf of Mexico (O'Ferrell et al., 2024)
- **2) Methods from animal movement ecology:**
 - State-space models; hidden Markov models
 - Blue whales (Hucke-Gaete et al., 2018); Pumas (Wang et al., 2015)

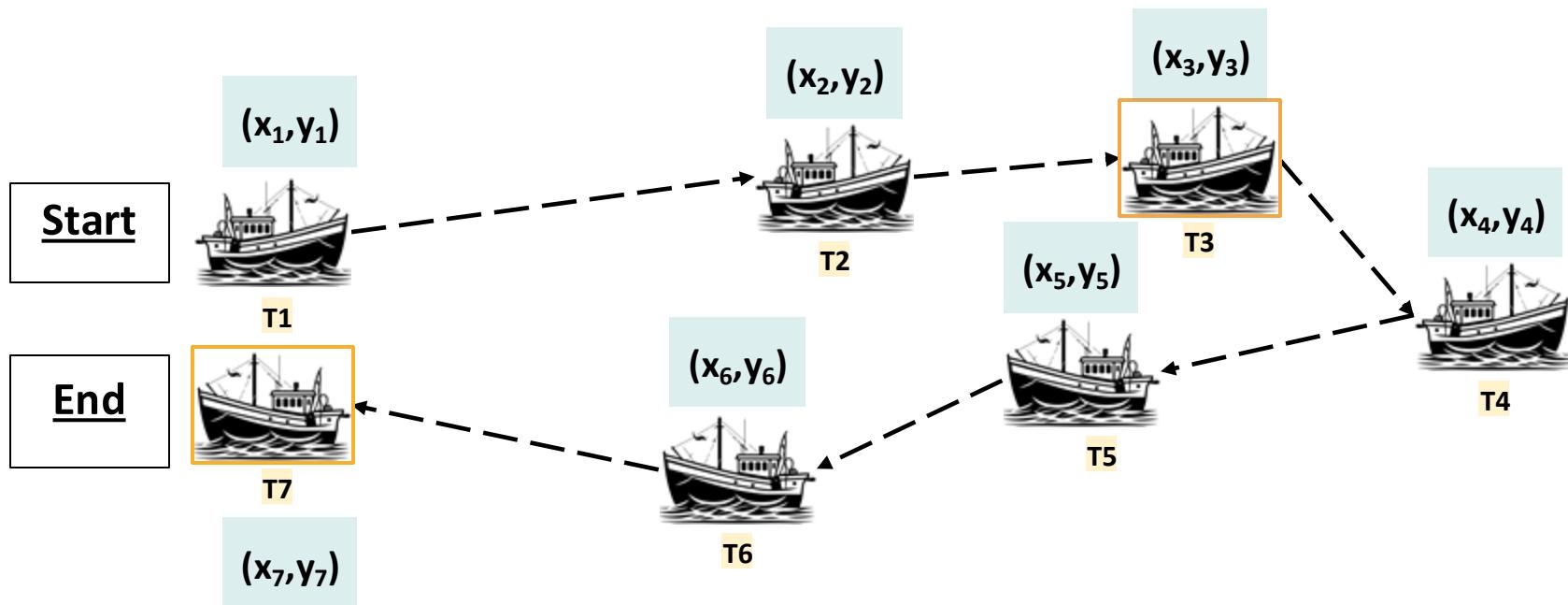
Methods - 1) State Space Model

- Data gives us...
 - Observed locations with measurement error



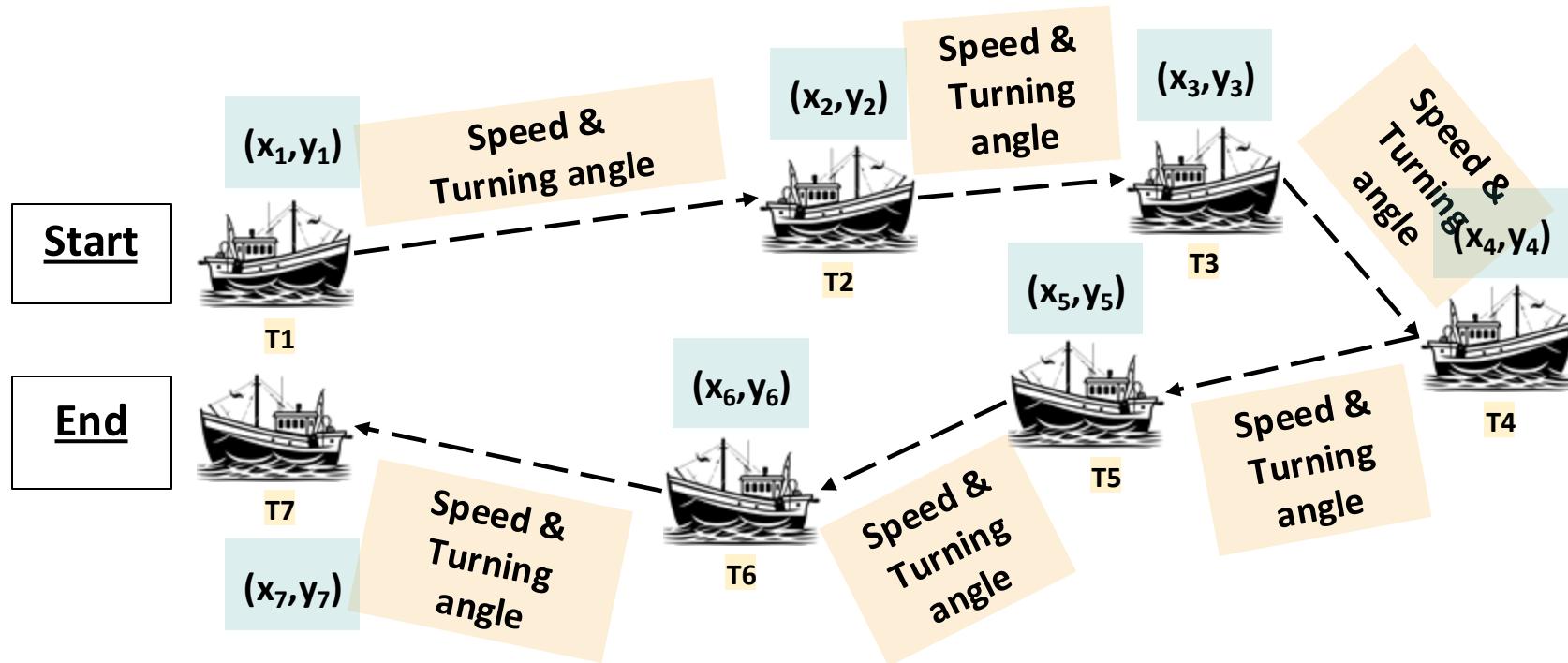
Methods - 1) State Space Model

- Fitting a SSM gives us unobserved true states:



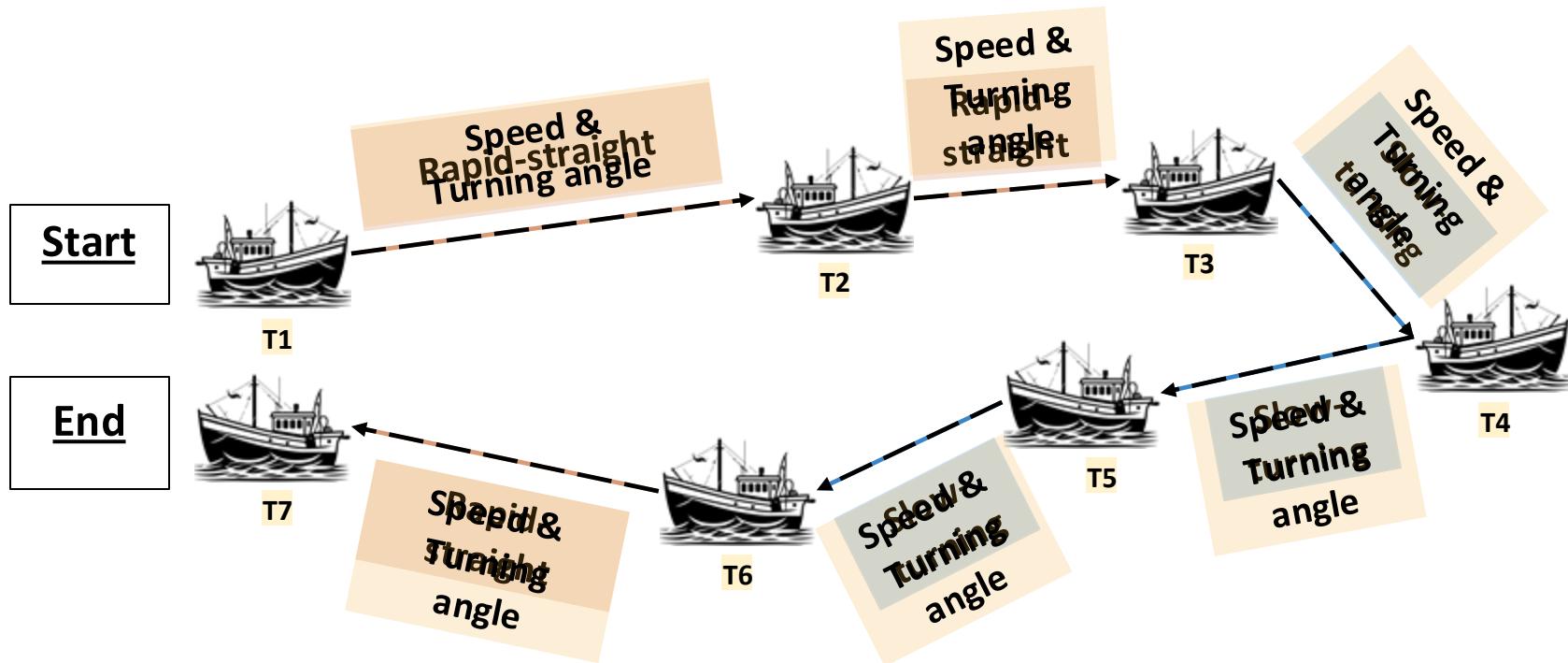
Methods - 1) State Space Model

- Fitting a SSM gives us unobserved true states:
 - 1) Estimated true locations with regularized data



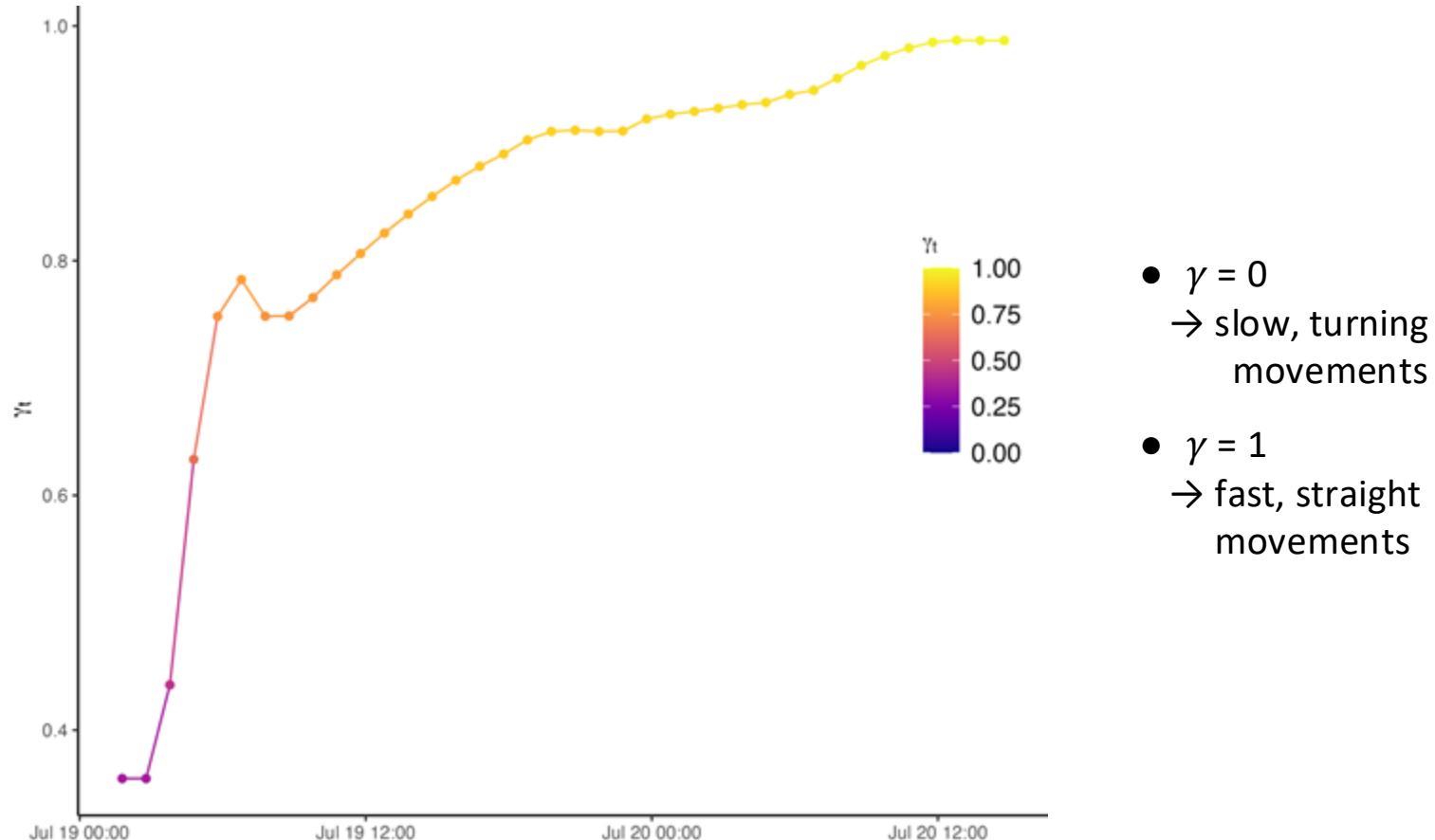
Methods - 1) State Space Model

- Fitting a SSM gives us unobserved true states:
 - 1) Estimated true locations with regularized data
 - → calculated movement metrics

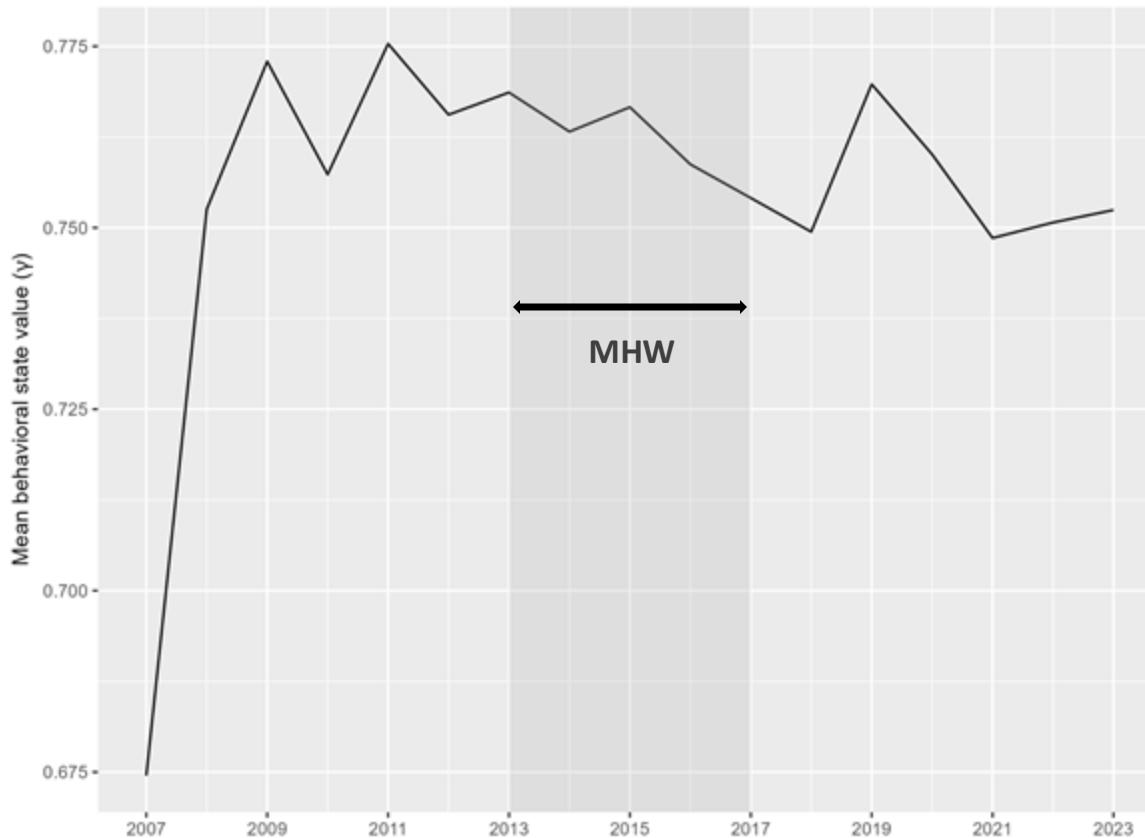


Preliminary Results - 1) State Space Model

Estimated Continuous Behavioral States for Salmon Trip ID 16578



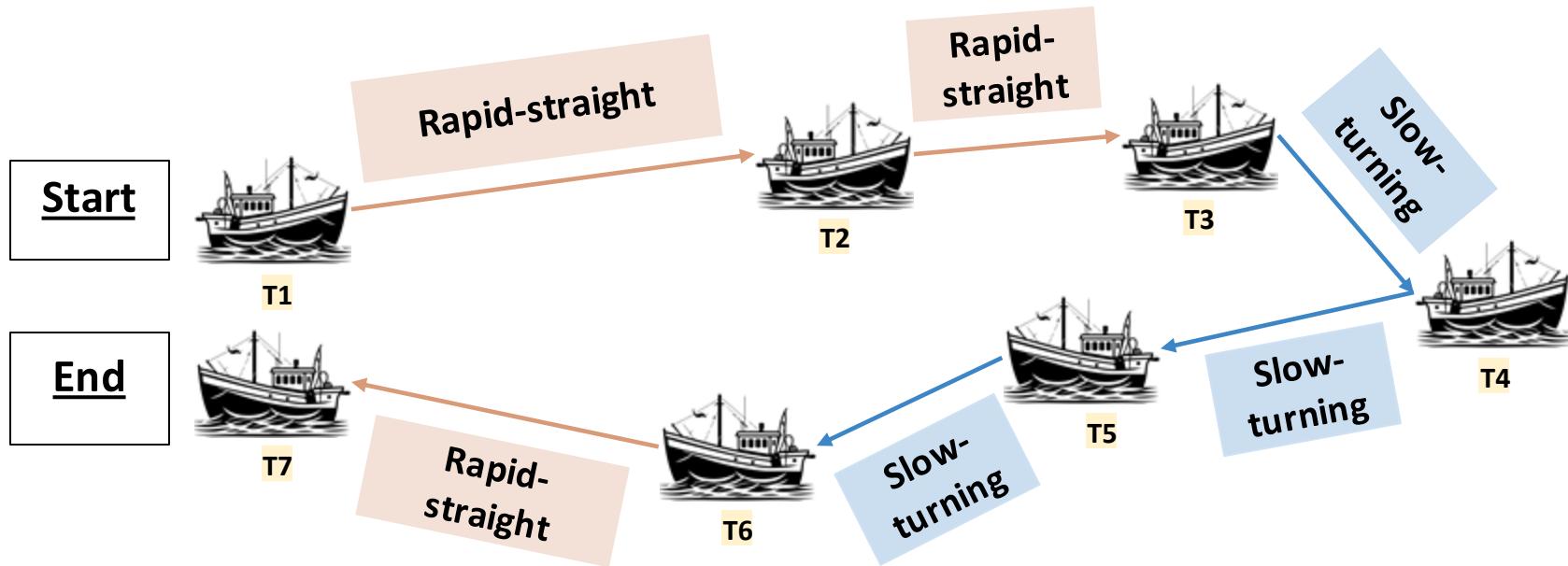
Preliminary Results - State Space Model



- Increasing time spent “foraging” during MHW years
- Does foraging mean “searching” or “fishing”?
- **Issue:** model does a poor job estimating distinct behaviors

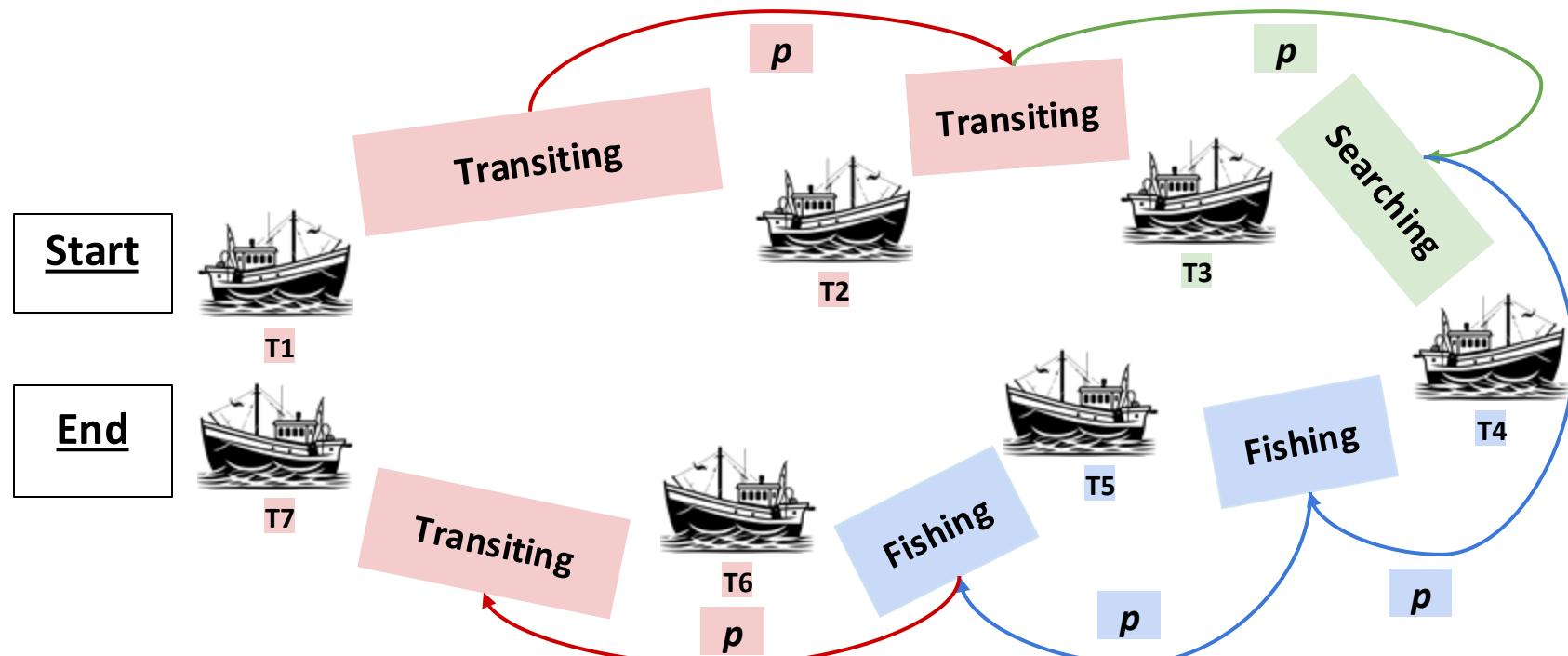
Methods - 2) Hidden Markov Model

- Previously, fitting a SSM gave us continuous estimated behavioral states at each timestep



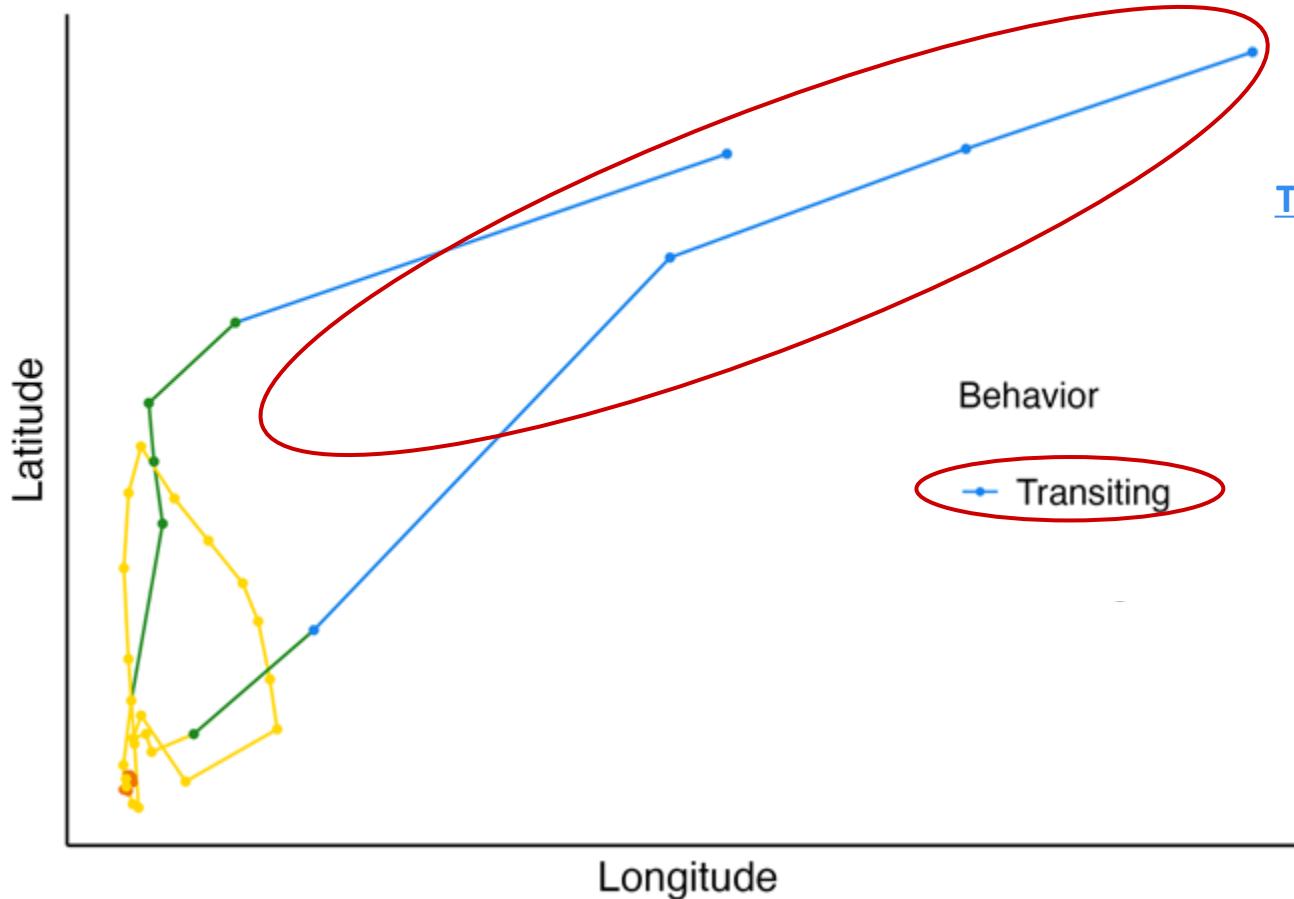
Methods - 2) Hidden Markov Model

- Now, fitting a HMM gives us...
 - Distinct estimated behavioral states at each time step
 - Probabilities of transitioning from one behavior to the other



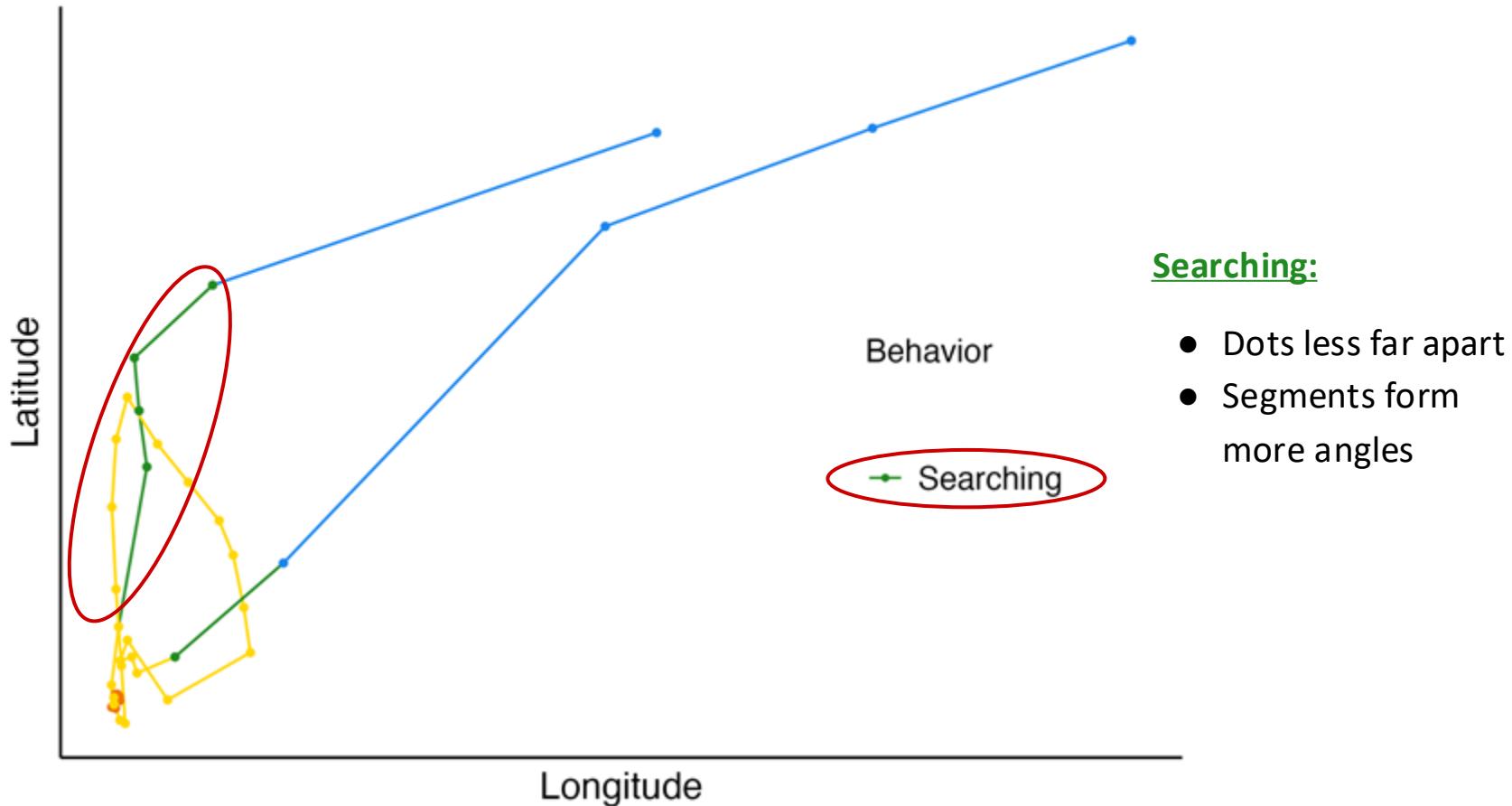
Preliminary Results - 2) Four State Hidden Markov Model

Estimated Behavioral States for Salmon Trip ID 16575



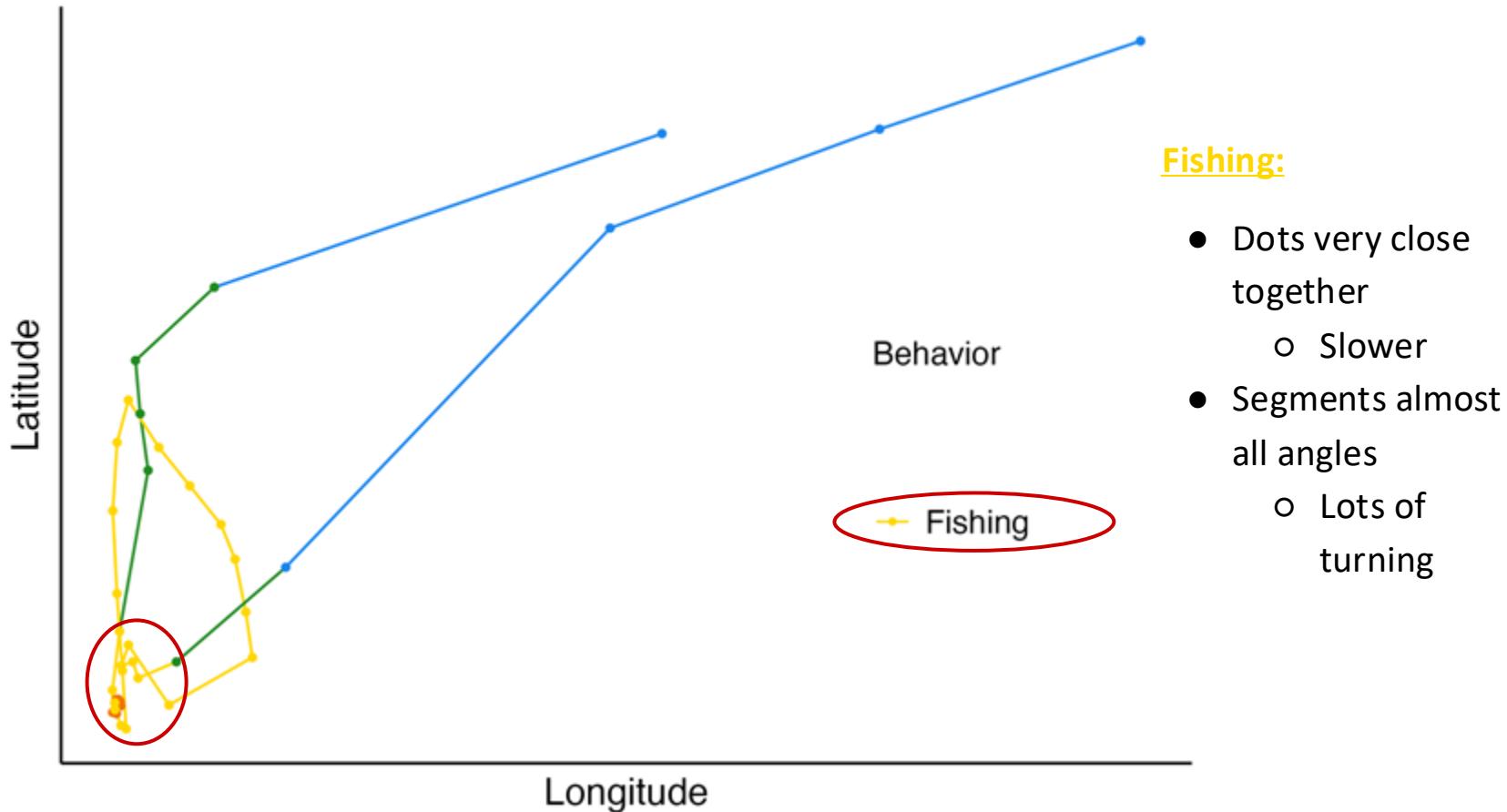
Preliminary Results - 2) Four State Hidden Markov Model

Estimated Behavioral States for Salmon Trip ID 16575



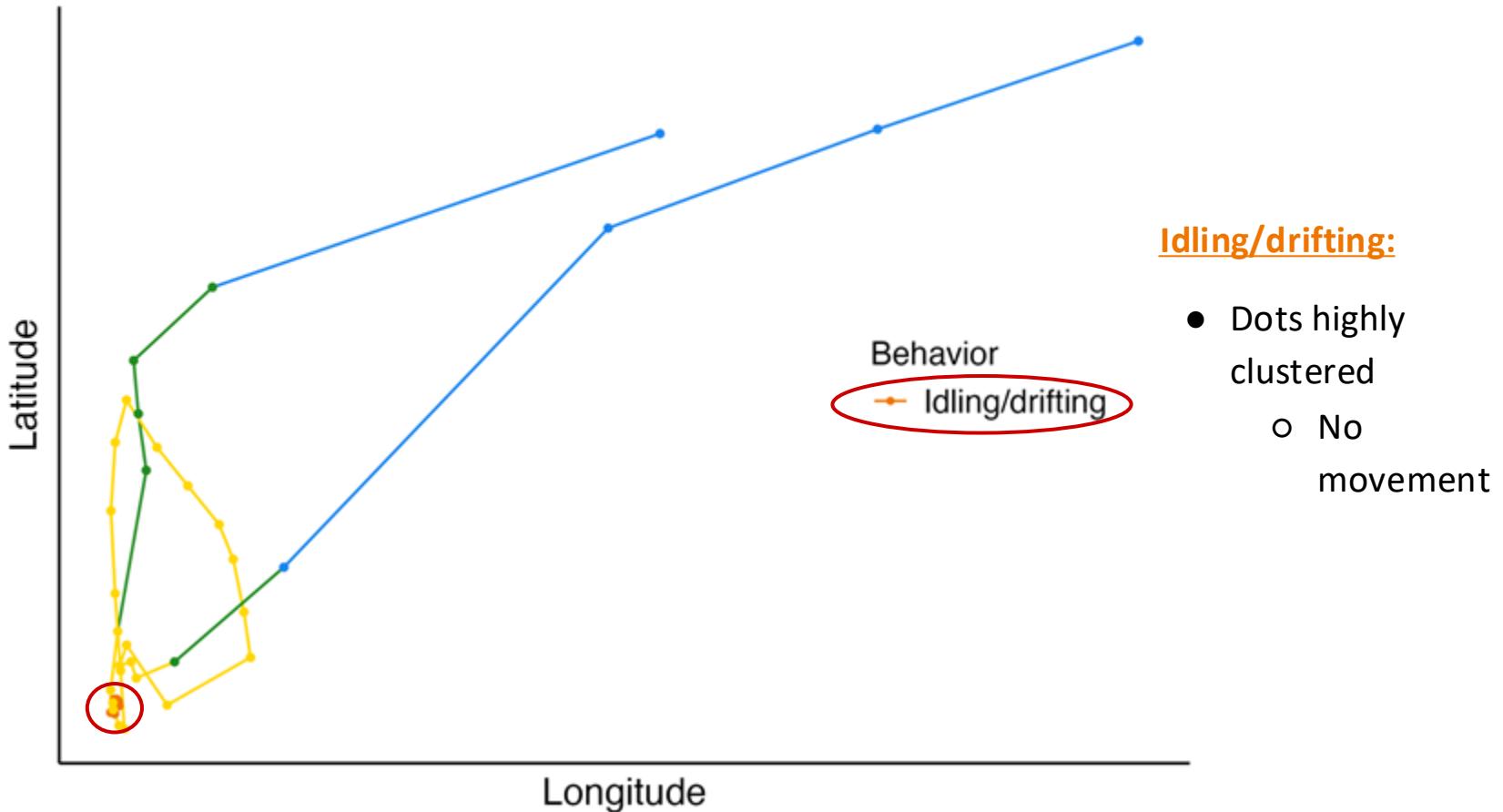
Preliminary Results - 2) Four State Hidden Markov Model

Estimated Behavioral States for Salmon Trip ID 16575



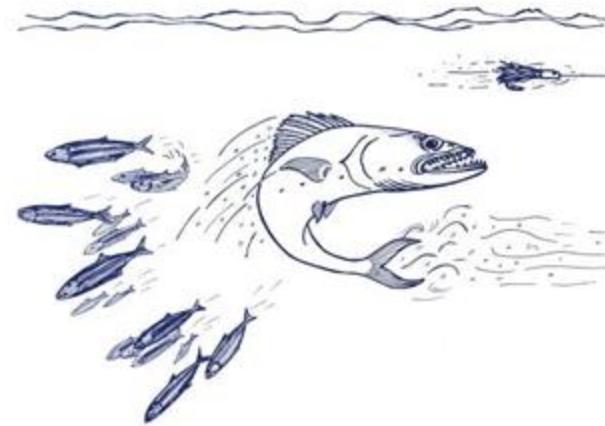
Preliminary Results - 2) Four State Hidden Markov Model

Estimated Behavioral States for Salmon Trip ID 16575



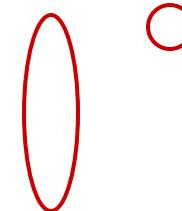
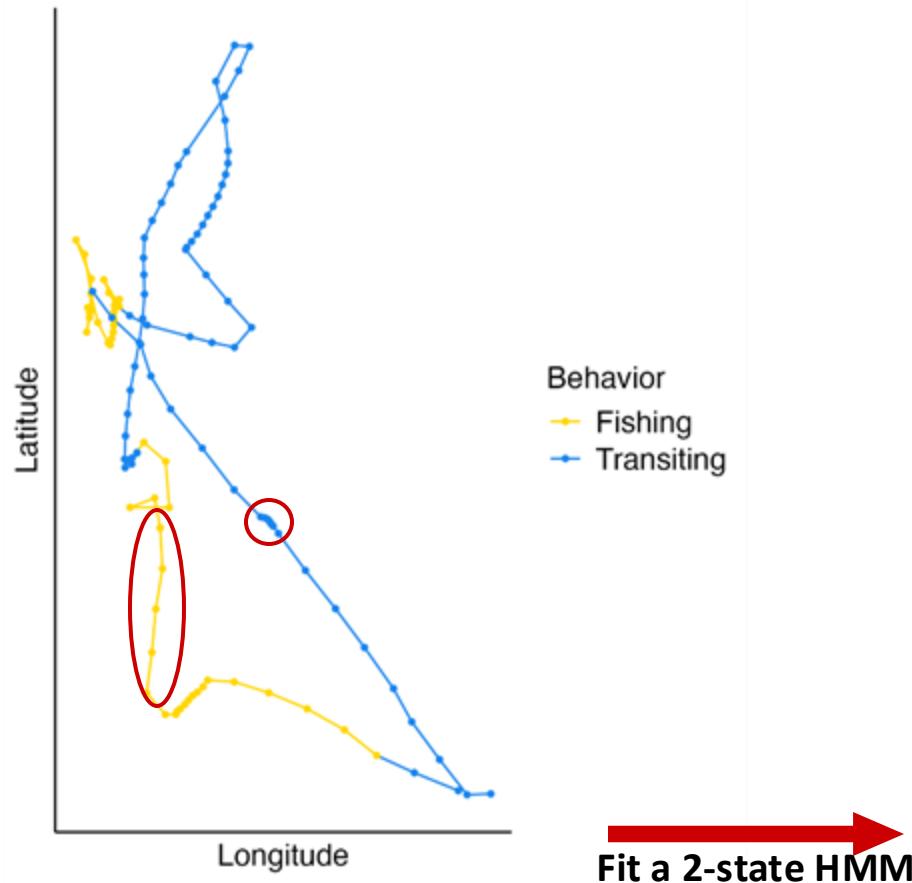
Methods - 3) Model Validation

- Issue: Pacific salmon ocean troll fishery has no available data with which to validate estimated fisher behaviors
- Solution: Validate estimated behaviors with independent data sources
 - 1) Logbook records from the Pacific albacore troll fishery
 - Similar to the salmon troll fishery
- Methods:
 - 1) Regularize data with a SSM
 - 2) Estimate behavioral states with a HMM
 - 2 state model
 - 4 state model



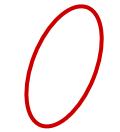
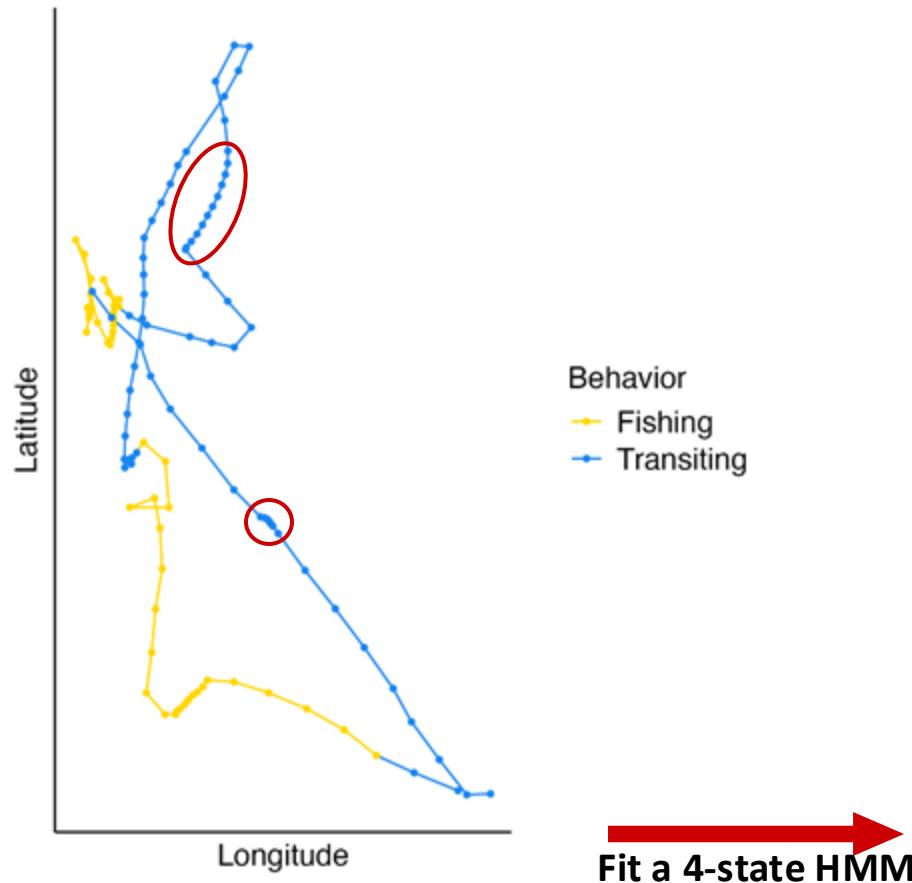
Preliminary Results - 3) Two State Model Validation

Logbook States for Albacore Trip ID 43390

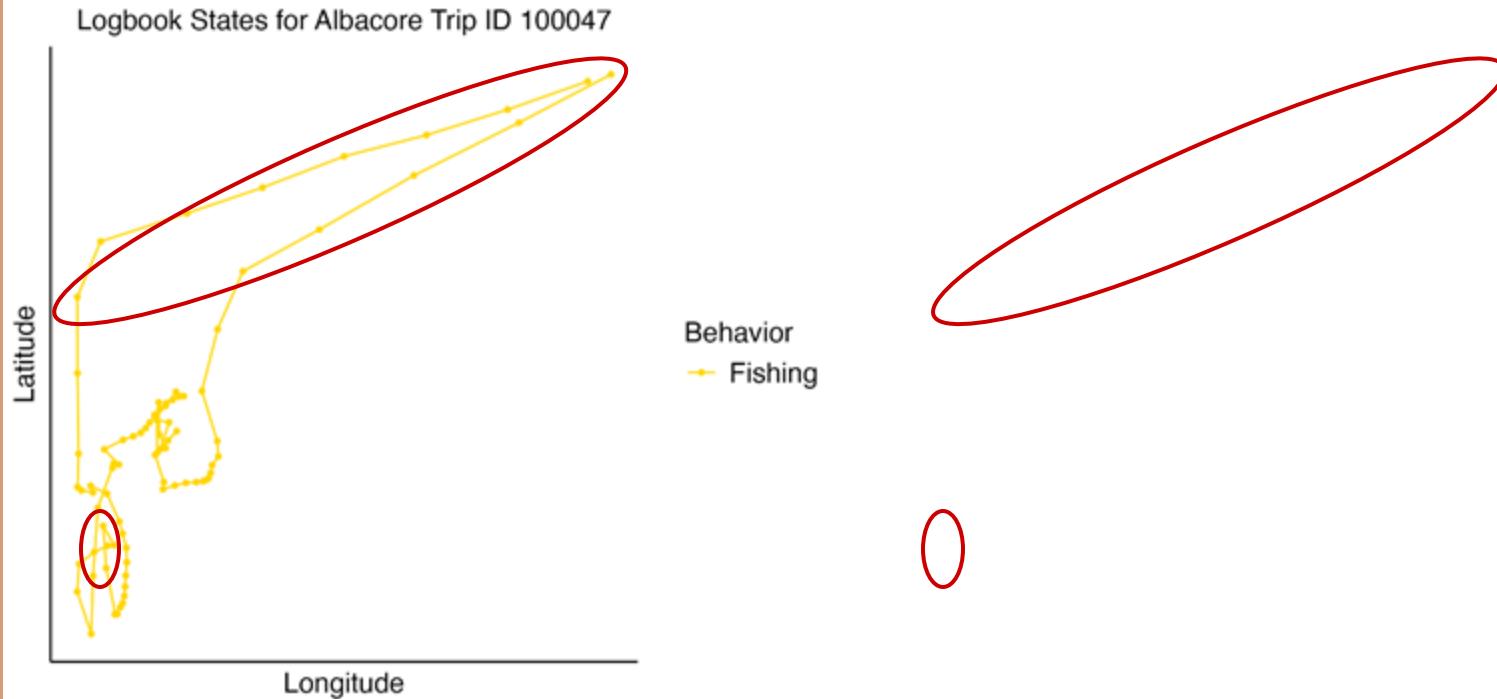


Preliminary Results - 3) Four State Model Validation

Logbook States for Albacore Trip ID 43390

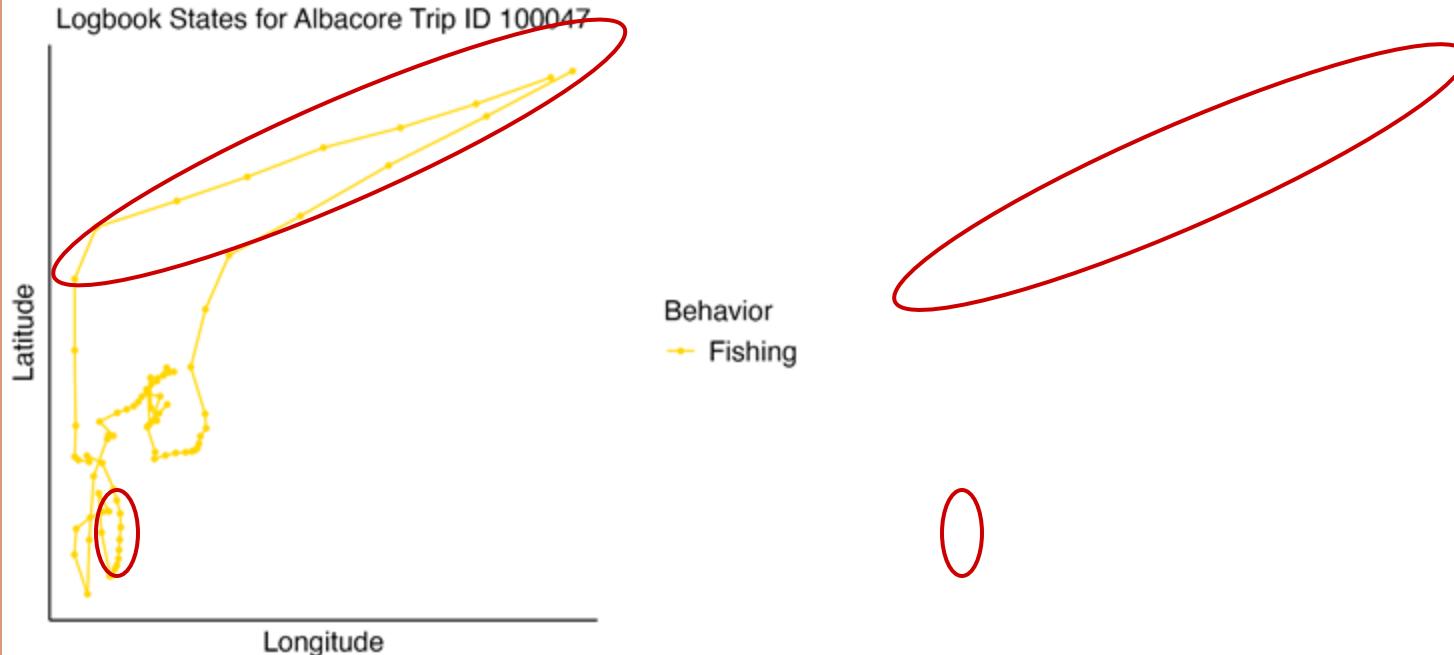


Preliminary Results - 3) Two State Model Validation



Fit a 2-state HMM

Preliminary Results - 3) Four State Model Validation



Fit a 4-state HMM

Preliminary Results - 3) Model Validation

- Reasons for discrepancies include:
 - Albacore logbook data is very noisy
 - Some trip data is more “useful” than others
 - Relies on fisher to note down activity and when it switches
 - Coarse characterization of trip activities:
 - Temporally (1 observation/day)
 - Per behavior

Concluding Thoughts

- **Methodological benefits:**
 - Uses less data
 - ~ 33% of federally managed fisheries have logbook data
 - Uses higher resolution data
 - 1 observation/hour as opposed to 1/day
 - Can be transferred to any fishery
- **Methodological challenges:**
 - Run time increases with the addition of behavioral states and covariate
 - Ability to differentiate between fishing and searching
 - Lack of variance in turning angle between the two behaviors
- **Next steps:**
 - 1) Interview commercial salmon fishers
 - 2) Use groundfish observer data



Thank you!

cacourtier@ucdavis.edu